

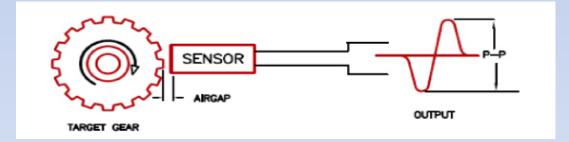
AI-TEK Active Sensors

Principles of Operation

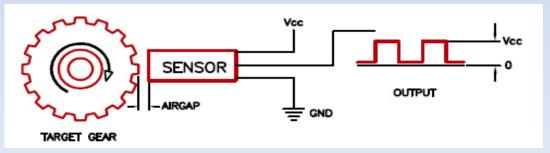
Al-TEK Instruments, LLC • 152 Knotter Drive, P.O. Box 748 • Cheshire, CT USA 06410 Tel: 203-271-6000 • Fax: 203-271-6200

www.aitekinstruments.com

- Speed sensors bridge the gap between the mechanical and electrical world. They produce a frequency proportional to the speed of the target.
- Al-Tek offers *two* basic sensor technologies that can be used in a large variety of applications.
 - Variable Reluctance (Passive)



Hall Effect (Active)

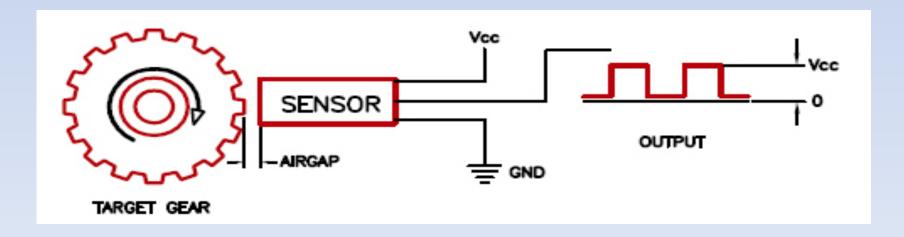


Hall Effect – AKA Zero Speed and Active Sensors



Hall Effect Sensors

- Is an active, powered device that produces an output signal regardless of target speed from zero to 15kHz+
- It includes a silicon chip that has high level of circuit integration leading to high reliability
- Typical output from a Hall Effect Sensor is Digital, square-wave output; amplitude is independent of speed
- 3 wire connection (single channel), 5 wire connection (dual channel with direction)
- Very stable over wide temperature range -40°C to + 125°C

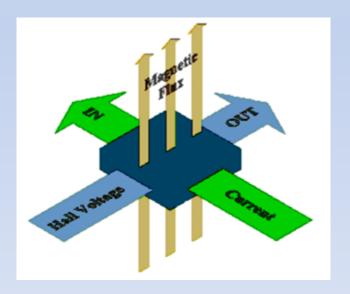


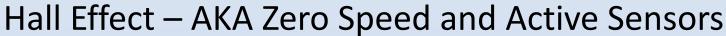
Al-TEK Sensor Training Hall Effect – AKA Zero Speed and Active Sensors



Principle of Operation.

- Basic building block of a hall effect sensor is the hall generator
- ➤ An output voltage is produced when the hall generator is exposed to magnetic flux and a bias current.



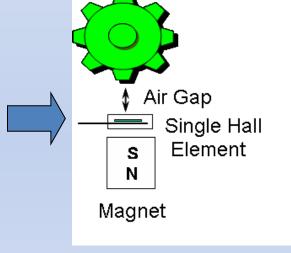


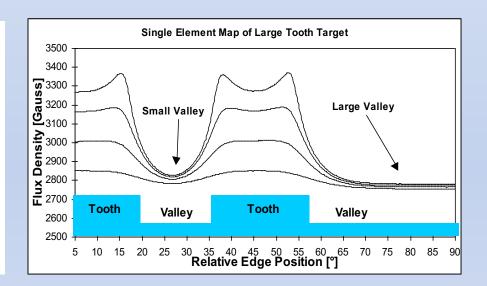


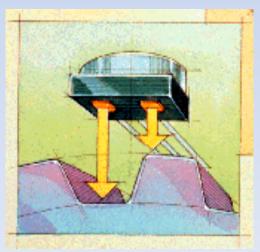
Principle of Operation — Single Element vs . Differential

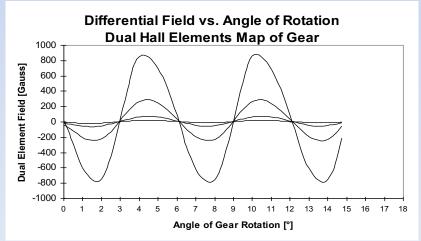
Single Element

RH Series – no need for alignment









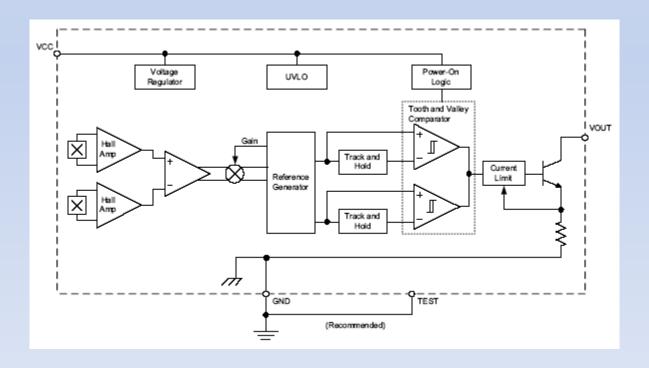


BH, DH Series – requires alignment



Principle of Operation; Differential.

Typical block diagram of differential amplifier circuit for BH and DH sensors





Advances in Switching Technology BH and DH Sensors

Self calibration, which normalizes signal amplitude, is accomplished through

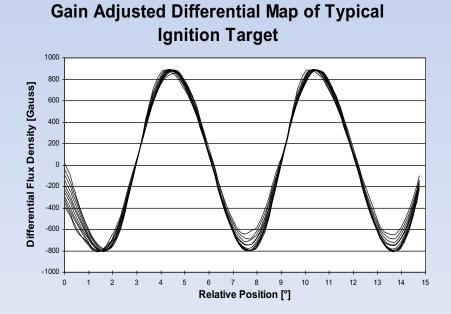
Automatic Gain Control (AGC).

AGC is enabled at power-up to allow learning of the gear and then is disabled to prevent transient events from affecting device operation.

Differential Map of Typical Ignition
Target

Target

1000
800
400
400
400
-1000
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
Relative Position [°]



Tachometer Application



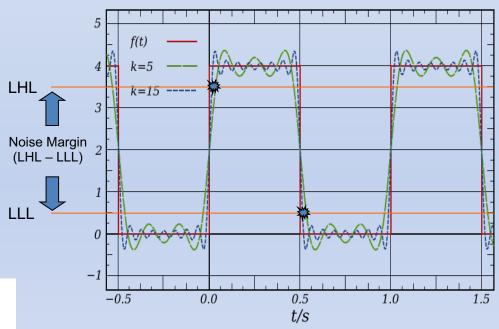
Logic Thresholds – Active (Hall Effect) Sensor Output - Square Wave

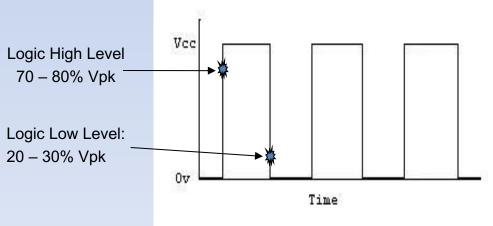
Logic thresholds:

Define a viable sensor pulse

Use to create filter to reject noise

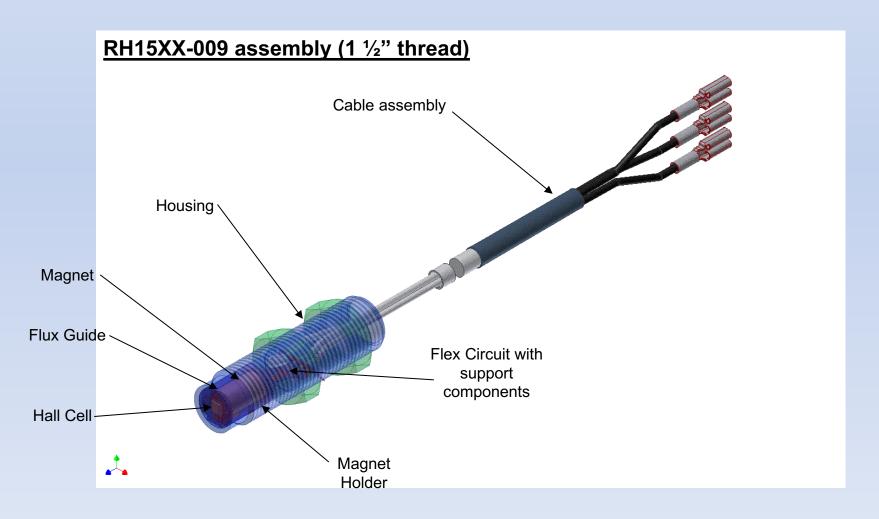
LHL – LLL = Noise Margin







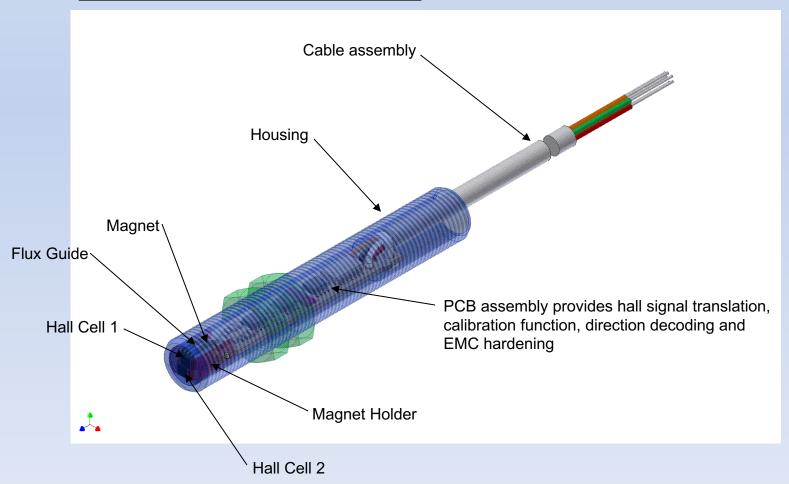
Typical RH Series Construction Single Channel, Single element





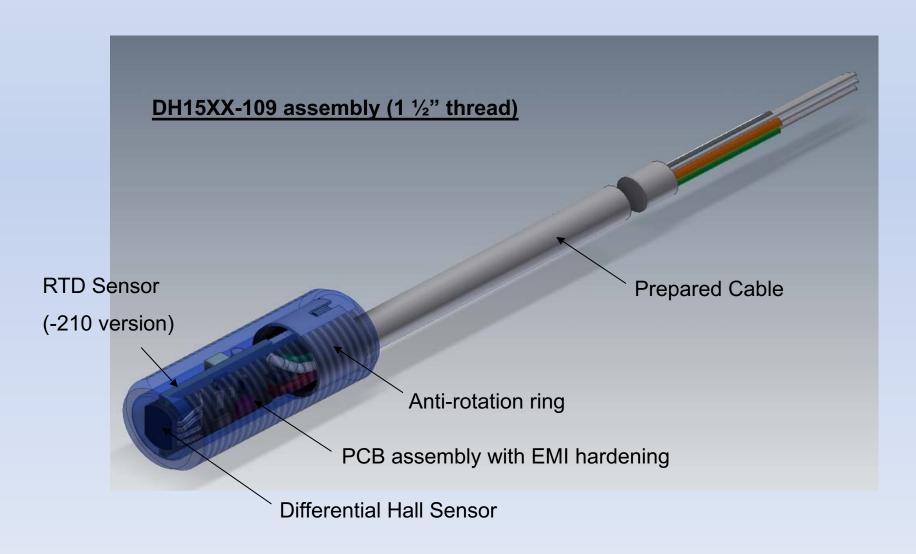
Typical BH Series Construction Dual Channel, Bi-directional, Dual Differential

BH15XX-010 assembly (4" thread)





Typical DH Series Construction Single channel, Differential



Al-TEK Sensor Training Hall Effect – AKA Zero Speed and Active Sensors



Features

- High temperature range of -40 C to +125 C
- Wide range of supply voltage; 4.5-24Vdc (single channel) and 10-28 Vdc (dual channel)
- Two output options of Supply Tracking or TTL Compatible
- Increased air gap capability over VR
 Sensors; no loss of signal amplitude
- Output signal will react to the lowest increment of speed without loss of amplitude
- High level of intrinsic noise immunity
- Vibration Immunity

Benefits

- Easy installation
- No alignment for RH series sensors
- High reliability
- Direction Indication
- Reverse voltage protection, up to -30
 Vdc, to prevent damage if mis-wired

Limitation

- Temperature Max temp is 125C
- Not good with axial trajectory targets

Application Considerations – Hall Effect



Which active sensor is right for your application?

PERFORMANCE	RH SERIES	DH SERIES	BH SERIES
Zero speed to 15kHz operation	X	X	X
Standard gear tooth sensing	X	X	X
Fine, 32 DP Capability		X	X
Single tooth/valley target		X	X
No installation alignment	X		
Extended airgap (0.100"+ for 12DP and coarser targets)		X	X
General noise immunity	X	X	X
EMI Hardened		X	X
High tolerance to target run-out		X	X
Self-calibrating		X	X
Direction Sensing			X
Lowest cost	X		
Temperature Sensing		Х	

Application Considerations – Hall Effect



TTL Compatible Sensor

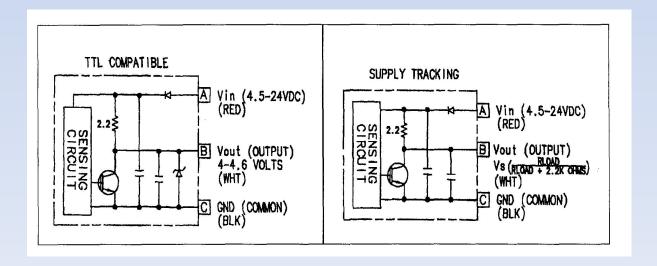
- For use with TTL input circuits. Less sensitive to load capacitance than Supply Tracking.
- The disadvantage of a "TTL Compatible" sensor is more noise susceptible

Supply Tracking Sensor

means that the output voltage tracks the supply voltage

Advantage/Disadvantage

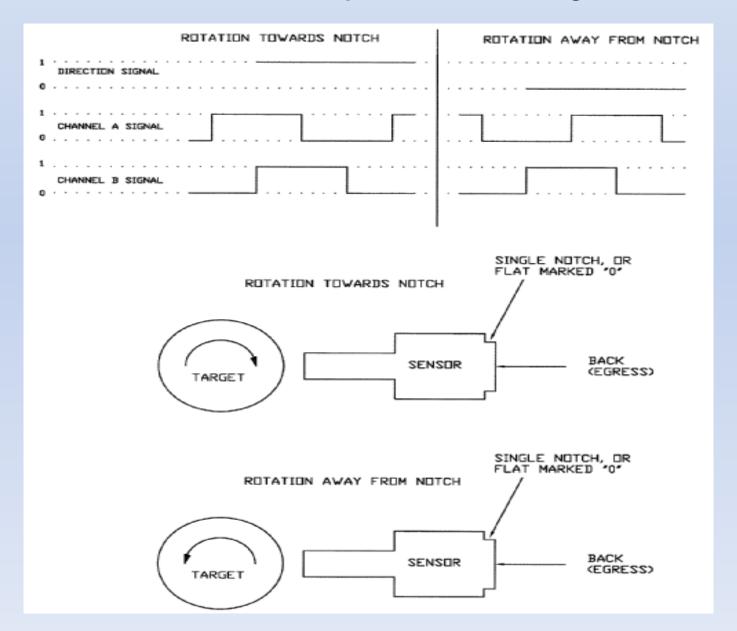
- Advantage: Supply Tracking is more noise immune compared to the "TTL Compatible" sensor whose zener diode clamps the Logic 1 voltage to approximately 4-4.6Vdc.
- Disadvantage: Supply tracking is more sensitive to high capacitance. High Capacitance is typically found in applications with very long distances between sensor and instrument location and can cause the sensor to fail to switch.



Application Considerations – Hall Effect



BH Series, Bi-Directional A-B Output Channel Phasing / Direction Indication

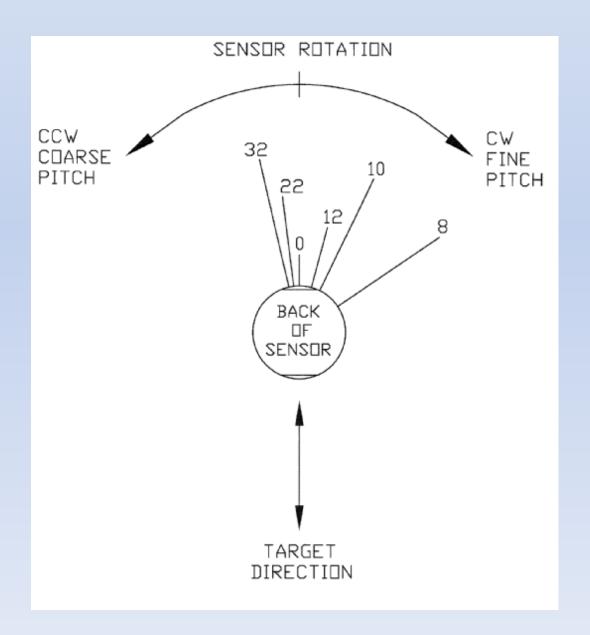


Application Considerations – Hall Effect



BH Series, Bi-Directional

Diametral Pitch Phase Adjustment



Application Considerations – Hall Effect



Why do I need a Digital Signal Distance Amplifier (DSDA)?

- For use with any AI-TEK active sensor or other brands that support TTL or Supply tracking sourcing output styles.
- When a sensor works fine locally (short cable) but fails at distance or high frequency.
- You may need a DSDA if an application has a combination of these factors:
 - Active Sensor wiring run exceeds 500 ft
 - Mutual capacitance between any 2 conductors exceeds 12,000pf (>>25pf/ft)
 - Load capacitance at the input device (PLC, etc) exceeds 1000pf 3,000pf
 - Signal frequency exceeds 1000Hz

Application Considerations – Hall Effect



Digital Signal Distance Amplifier (DSDA) Hints to avoid needing one

- Follow best industry practices for wiring to help reduce the need for a DSDA.
- If possible run signal wires separate from power and ground
- Mutual capacitance multiplies with each wire pair. For example 1 pair = 1X, triad
 = 2X, quad = 3x mutual value.
- Larger wire sizes increase mutual capacitance
- Use 20 22 AWG wire with minimum capacitance and resistance
- Ensure large amounts of capacitance (above 1000 3000 pf) are not installed between the signal and ground or power.
- Balance signal load for bi-directional (BH series) sensors

AI-TEK Sensor Product Overview



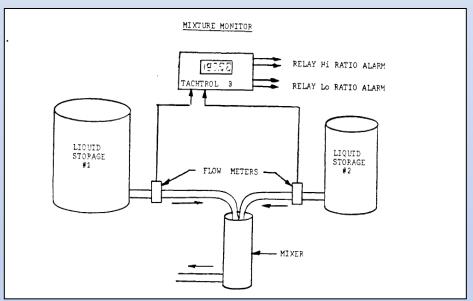
New Digital Signal Distance Amplifier (DSDA)

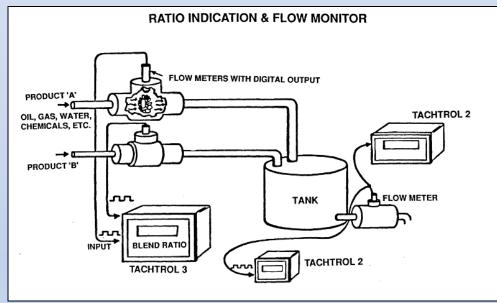
Features

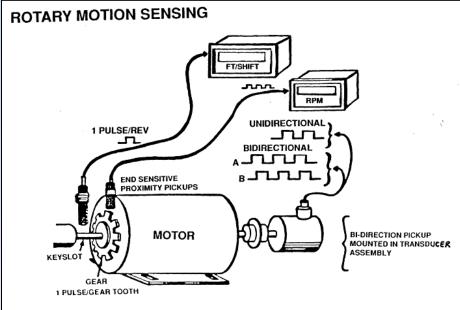
- The new AI-TEK DSDA's are designed for use with active sensors and serve to reduce line impedance, allowing cable runs of up to 3000ft.
- In some cases this represents a 10X improvement over installations not currently using a DSDA.
- Available in TTL and Supply Tracking outputs

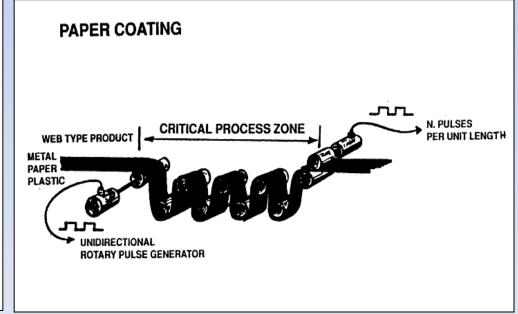




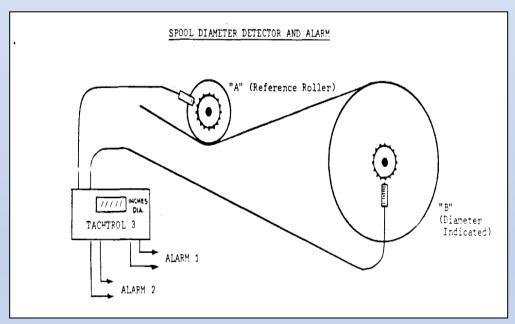


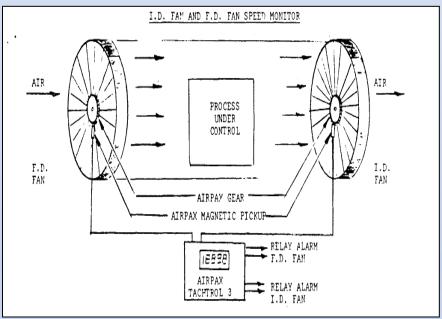


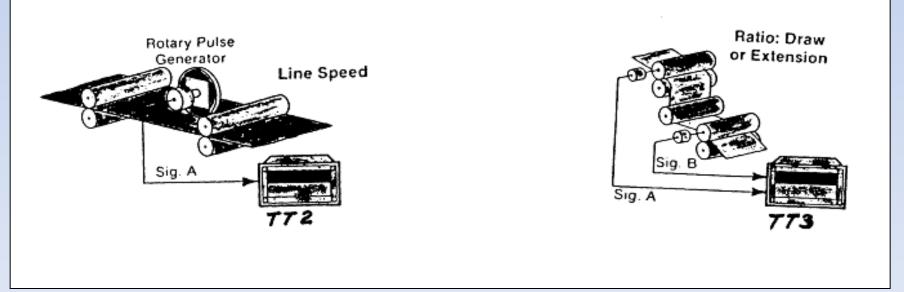




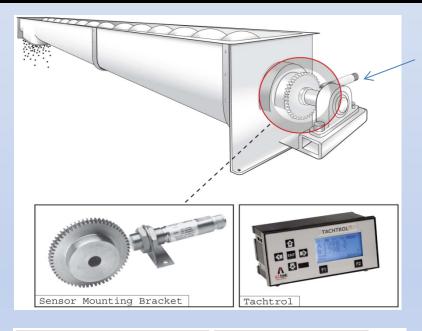


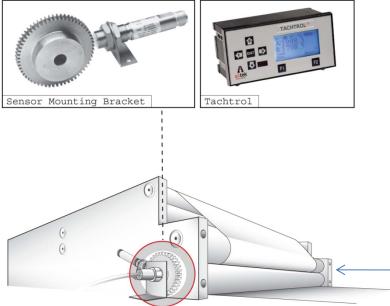






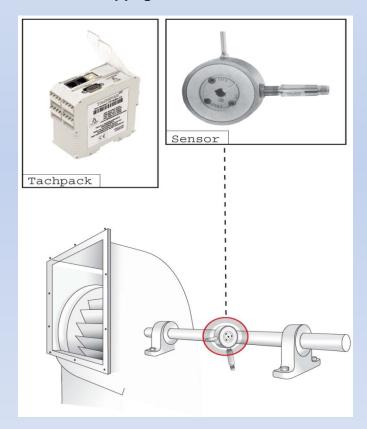






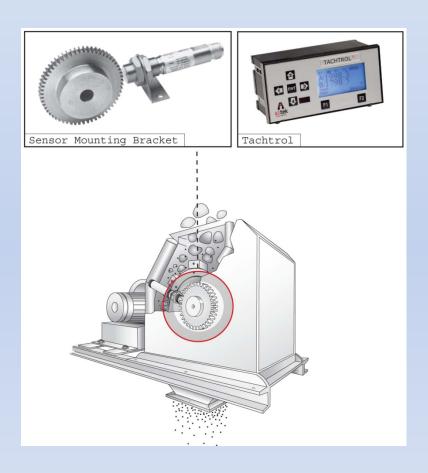
Detecting speed on screw conveyors

Detecting over-speed, under-speed or stoppage of fans and blowers

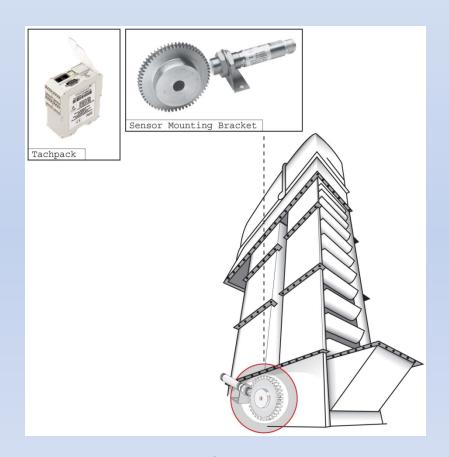


Monitoring web press



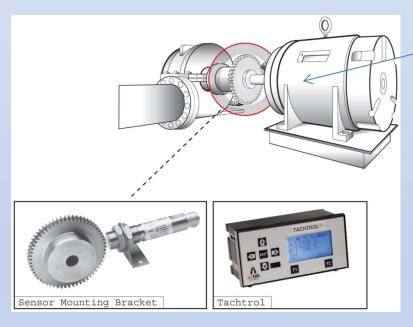


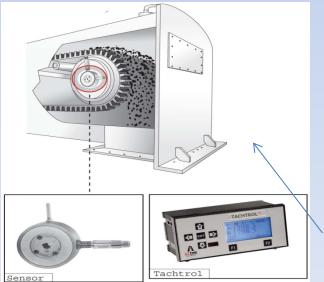
Monitoring hammer mill speed



Monitoring shaft speed slowdown or belt slippage of a bucket conveyor

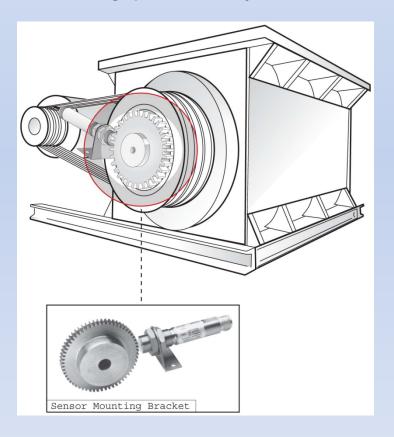






Pump application monitoring for reverse rotation or jam

Monitoring speed of a rotary air lock



Monitoring shaft speed and coal feed on volumetric coal feeder

Accessory Products



Gears



Split Gears

Split gears provide a convenient and simple means of installation where shaft disassembly is not feasible. The two halves of the gear are fastened with clamping screws. All split gears are 12 diametral pitch, 14.5° pressure angle.

Solid Gear

Al-Tek also offers a 20 diametral pitch, 14.5° pressure angle, solid steel gear. This gear can be rebored to fit shaft diameters up to 1.375". It is secured to the shaft with 2 set screws.

Cable Assemblies



Connectors and Cable Assemblies

- Al-Tek stocks a selection of connectors and cable assemblies for your convenience.
- Complete cable assemblies include the connector and 10' of recommended wiring for use with Al-Tek equipment.
- All wiring is insulated, and wrapped with braided or copper shield and jacketed in long-lasting PVC, Teflon or polyolefin insulation.
- Alternate cable length is 50', is available

Tachometer Transducer



Complete Sensing Solution

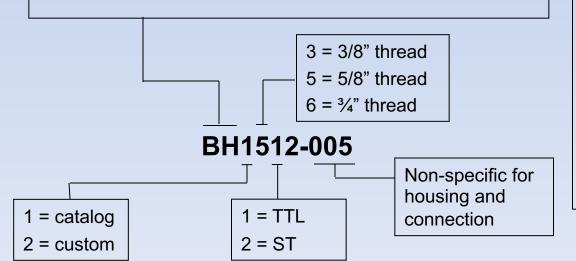
- Includes Sensor VR or Hall
- Mounts on shafts up to 2 in dia.
- (2) types of mounting Taper-Lock or Sleeve Type.
- Great for mounting long shafts and cannot allow close air gaps

AI-TEK Sensor Product Overview



Active / Hall Effect Part Numbers

- **H Series** single channel, differential, no calibration, early 1990's to mid 2005
- •RH Series single channel, single element, low-level calibration, mid 2005 to present
- •BH Series dual channel bi-directional, EMC, differential, high-level calibration, mid 2004 to present
- •DH Series single channel, EMC, differential, high-level calibration, late 2011 to present



Passive / VR Part Numbers

- •70082-xxxx-xxx Automotive / Side Look
- •70083-xxxx-xxx Automotive / Custom - 3/4"
- •70084-xxxx-xxx Automotive / Military / Custom – 5/8"
- •70085-1010-xxx •70085-8080-xxx Std Airpax / AI-TEK P/N's
- •70085-3030-xxx AI-TEK / IEC EX
- •086-xxx-xxxx MIL-AERO / Custom

Al-Tek Sensor Training Key Sensor Selection Criteria



Target Info				
Outside Dia.	# of Teeth (or holes)	Diametral Pitcl	h (#T+2/OD in.)or module	
Material				
Mounting and Da	<u>ita needed</u>			
Max speed measured Max Min	d Min. speed meas	sured Surfa	ce spd(OD* Π * RPM/60)	
IVIAX IVIIII				
			Active Signal Type	NPN PNP
Load on Sensor(ohm	ns) Thread size	length		
Environment				
Temperature	Atmosphere (air, oil, ste	am, pressure etc	.)	
Certification UL	FM ATEX ′	Termination (conf	nector, cable, wire leads) _	
Other				
Sales Detail				
Volume/year	_ Target price D	Oue Date	Competition	

Common Conversions



Formulas

$$\mathbf{f} = \text{RPM} \times \text{PPR}/60 = \text{ss} \times \text{PPR}/\Pi \times D$$

$$\mathbf{f} = \text{UPM} \times \text{PPU}/60 = \text{UPH} \times \text{PPU}/3600$$

RPM =
$$60 \times f/PPR = 60 \times ss / \Pi \times D$$

PPR =
$$(D \times DP) - 2 = 60 \times f/RPM$$

PPR =
$$f \times \Pi \times D/ss$$

ss = RPM x
$$\Pi$$
 x D/60=f x Π x D/PPR

$$\mathbf{D} = (PPR + 2)/DP = ss \times PPR/f \times \Pi$$

$$\mathbf{DP} = (PPR + 2)/D = 25.4/M$$

$$M = 25.4/DP = 25.4 \times D/(PPR+2)$$

Definitions

f = frequency in Hz or cycles per second (cps)

RPM = rotary speed in revolution per minute

PPR = pulses per revolution or # of gear teeth

PPU = pulses per unit measure

 $\Pi = pi, 3.14$

UPM = unit measure per minute

UPH = unit measure per hour

ss = surface speed in inches per second (ips)

D = outside diameter of target in inches

DP = diametral pitch, # teeth in 1 inch of pitch diameter

M = metric module, pitch diameter in mm divided by # of gear teeth

AI-TEK Instruments Product Training



The End Thank you