## **Specifications**

**Power Supply** 

Power Supply Voltage:

4.5 - 24 Vdc

**Power Supply Current:** 

50 mA maximum

**Outputs** 

Output Voltage:

Essentially square wave fanout to 10 TTL inputs

Supply Tracking: (See Figure 1)

50% ±15 % duty cycle

Logic 0:

+.6 Vdc maximum

Logic 1:

 $V_0 = \frac{V_S \times R_L}{R_L + 2.2k}$ 

**Output Impedance:** 

2.2K Ohms ±5%

**Output Current:** 

20 mA sink maximum

**Output Current - Short Circuit:** 

5 mA maximum with 10V power supply

Mechanical

**Target Frequency:** 

0 to 15 kHz

Target Air Gap:

.005 to .030 with a 24 diametral pitch gear

.005 to .040 with a 20 diametral pitch gear

.005 to .070 with a 12 diametral pitch gear

.005 to .100 with an 8 diametral pitch gear

**Environmental** 

**Operating Temperature:** 

-25°C to + 125°C (105°C Cable)

**Materials** 

Housing:

300 series stainless steel

Leads:

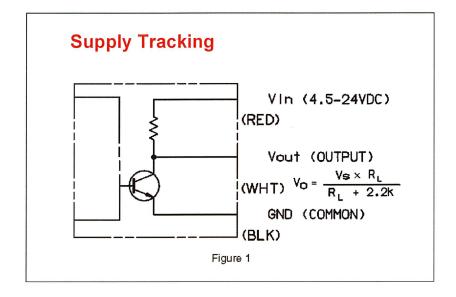
AWG #24 Teflon, 200°C

Cable:

AWG #26 PVC, 105°C

Rotational alignment of sensing face is not re-

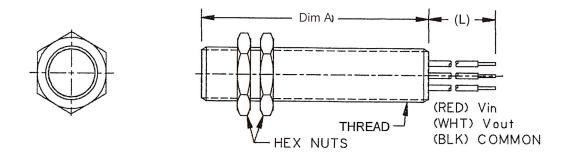
quired for optimum output signal



Note: Will work with any Al-Tek Tachometer.

## RH Series Zero Velocity - Magnetic Hall Effect Sensors - 3/8 Diameter

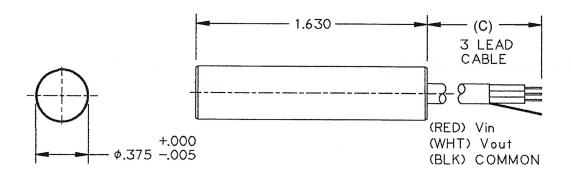
## **Fully Threaded**



Part Num.	Thread	Cable Length (C)	Lead Length (L)	Dimension A
RH1320-001	.375-32 UNEF-2A		12 (304)	1.630
RH1320-003	.375-32 UNEF-2A	10 ft. (3.05 m)		1.630
RH1320-009	.375-24 UNF-2A	_	12 (304)	1.630
RH1320-010	.375-24 UNF-2A	10 ft. (3.05 m)	_	1.630
RH1320- 012	.375-24 UNF-2A	10 ft. (3.05 m)	_	3.000

New Weight: 0.7 oz. max.

## **Round Body**



Part Num.	Cable Length (C)	Lead Length (L)	
RH1320-005		12 (304)	
RH1320-006	10 ft. (3.05 m)	_	